

Every BDD node can be interpreted as a mapping from valuations to truth values: Traverse the BDD from the given node to a leaf node; for any node labelled with P take the 0-edge or 1-edge depending on whether $\mathcal{A}(P)$ is 0 or 1.

\Rightarrow Compact representation of truth tables.

OBDDs

OBDD (Ordered BDD):

Let $<$ be a total ordering of the propositional variables.

An OBDD w. r. t. $<$ is a BDD where every edge from a non-leaf node leads either to a leaf node or to a non-leaf node with a strictly larger label w. r. t. $<$.

OBDDs and formulas:

A leaf node $\boxed{0}$ represents \perp (or any unsatisfiable formula).

A leaf node $\boxed{1}$ represents \top (or any valid formula).

If a non-leaf node v has the label P , and its 0-edge leads to a node representing the formula F_0 , and its 1-edge leads to a node representing the formula F_1 , then v represents the formula

$$\begin{aligned} F &\models \text{if } P \text{ then } F_1 \text{ else } F_0 \\ &\models (P \wedge F_1) \vee (\neg P \wedge F_0) \\ &\models (P \rightarrow F_1) \wedge (\neg P \rightarrow F_0) \end{aligned}$$

Conversely:

Define $F\{P \mapsto H\}$ as the formula obtained from F by replacing every occurrence of P in F by H .

For every formula F and propositional variable P :

$$F \models (P \wedge F\{P \mapsto \top\}) \vee (\neg P \wedge F\{P \mapsto \perp\})$$

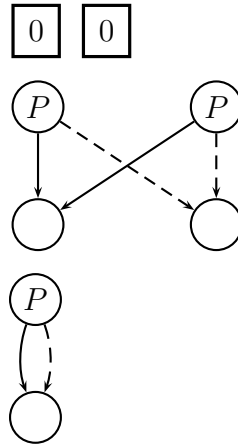
(*Shannon expansion* of F , originally due to Boole).

Consequence: Every formula F can be represented by an OBDD.

Reduced OBDDs

An OBDD is called *reduced*, if it has

- no duplicated leaf nodes
- no duplicated interior nodes
- no redundant tests



Theorem 2.20 (Bryant 1986) *Every OBDD can be converted into an equivalent reduced OBDD.*

Assumptions from now on:

One fixed ordering $>$.

We consider only reduced OBDDs.

All OBDDs are sub-OBDDs of a single OBDD.

Implementation:

Bottom-up construction of reduced OBDDs is possible using a hash table.

Keys and values are triples $(PropVar, Ptr_0, Ptr_1)$,

where Ptr_0 and Ptr_1 are pointers to the 0-successor and 1-successor hash table entry.

Theorem 2.21 (Bryant 1986) *If v and v' are two different nodes in a reduced OBDD, then they represent non-equivalent formulas.*

Proof. We use induction over the maximum of the numbers of nodes reachable from v and v' , respectively. Let F and F' be the formulas represented by v and v' .

Case 1: v and v' are non-leaf nodes labelled by different propositional variables P and P' . Without loss of generality, $P < P'$.

Let v_0 and v_1 be the 0-successor and the 1-successor of v , and let F_0 and F_1 be formulas represented by v_0 and v_1 . We may assume without loss of generality that all propositional

variables occurring in F' , F_0 , and F_1 are larger than P . By reducedness, $v_0 \neq v_1$, so by induction, $F_0 \not\models F_1$. Hence there must be a valuation \mathcal{A} such that $\mathcal{A}(F_0) \neq \mathcal{A}(F_1)$. Define valuations \mathcal{A}_0 and \mathcal{A}_1 by

$$\begin{aligned} \mathcal{A}_0(P) &= 0 & \mathcal{A}_1(P) &= 1 \\ \mathcal{A}_0(Q) &= \mathcal{A}(Q) & \mathcal{A}_1(Q) &= \mathcal{A}(Q) \quad \text{for all } Q \neq P \end{aligned}$$

We know that the node v represents $F \models (P \wedge F_1) \vee (\neg P \wedge F_0)$, so $\mathcal{A}_0(F) = \mathcal{A}_0(F_0) = \mathcal{A}(F_0)$ and $\mathcal{A}_1(F) = \mathcal{A}_1(F_1) = \mathcal{A}(F_1)$, and therefore $\mathcal{A}_0(F) \neq \mathcal{A}_1(F)$. On the other hand, P does not occur in F' , therefore $\mathcal{A}_0(F') = \mathcal{A}_1(F')$. So we must have $\mathcal{A}_0(F) \neq \mathcal{A}_0(F')$ or $\mathcal{A}_1(F) \neq \mathcal{A}_1(F')$, which implies $F \not\models F'$.

Case 2: v and v' are non-leaf nodes labelled by the same propositional variable.

Case 3: v is a non-leaf node, v' is a non-leaf node, or vice versa.

Case 4: v and v' are different leaf nodes.

Analogously. □

Corollary 2.22 F is valid, if and only if it is represented by $\boxed{1}$. F is unsatisfiable, if and only if it is represented by $\boxed{0}$.

Operations on OBDDs

Example:

Let \circ be a binary connective.

Let P be the smallest propositional variable that occurs in F or G or both.

$$\begin{aligned} F \circ G &\models (P \wedge (F \circ G)\{P \mapsto \top\}) \vee (\neg P \wedge (F \circ G)\{P \mapsto \perp\}) \\ &\models (P \wedge (F\{P \mapsto \top\} \circ G\{P \mapsto \top\}) \\ &\quad \vee (\neg P \wedge (F\{P \mapsto \perp\} \circ G\{P \mapsto \perp\}))) \end{aligned}$$

Note: $F\{P \mapsto \top\}$ is either represented by the same node as F (if P does not occur in F), or by its 1-successor (otherwise).

\Rightarrow Obvious recursive function on OBDD nodes
(needs memoizing for efficient implementation).

OBDD operations are not restricted to the connectives of propositional logic.

We can also compute operations of *quantified boolean formulas*

$$\forall P. F \models (F\{P \mapsto \top\}) \wedge (F\{P \mapsto \perp\})$$

$$\exists P. F \models (F\{P \mapsto \top\}) \vee (F\{P \mapsto \perp\})$$

and images or preimages of propositional formulas w. r. t. boolean relations (needed for typical verification tasks).

The size of the OBDD for $F \circ G$ is bounded by mn , where F has size m and G has size n . (Size = number of nodes)

With memoization, the time for computing $F \circ G$ is also at most $O(mn)$.

The size of an OBDD for a given formula depends crucially on the chosen ordering of the propositional variables:

$$\text{Let } F = (P_1 \wedge P_2) \vee (P_3 \wedge P_4) \vee \dots \vee (P_{2n-1} \wedge P_{2n}).$$

$$P_1 < P_2 < P_3 < P_4 < \dots < P_{2n-1} < P_{2n}: 2n + 2 \text{ nodes.}$$

$$P_1 < P_3 < \dots < P_{2n-1} < P_2 < P_4 < \dots < P_{2n}: 2^{n+1} \text{ nodes.}$$

Even worse: There are (practically relevant!) formulas for which the OBDD has exponential size *for every ordering* of the propositional variables.

Example: middle bit of binary multiplication.

Literature

Randal E. Bryant: Graph-Based Algorithms for Boolean Function Manipulation; IEEE Transactions on Computers, 35(8):677-691, 1986.

Randal E. Bryant: Symbolic Boolean Manipulation with Ordered Binary Decision Diagrams; ACM Computing Surveys, 24(3), September 1992, pp. 293-318.

Michael Huth and Mark Ryan: *Logic in Computer Science: Modelling and Reasoning about Systems*, Chapter 6.1/6.2; Cambridge Univ. Press, 2000.

2.10 FRAIGs

Goal:

Efficient manipulation of (equivalence classes of) propositional formulas.

Smaller representation than OBDDs.

Method: Minimized graph representation of boolean circuits.

FRAIG (Functionally Reduced And-Inverter Graph):

Labelled DAG (directed acyclic graph).

Leaf nodes:

labelled with propositional variables.

Non-leaf nodes (interior nodes):

labelled with \wedge (two outgoing edges) or \neg (one outgoing edge).

Reducedness (i. e., no two different nodes represent equivalent formulas) must be established explicitly, using

structural hashing,
simulation vectors,
CDCL,
OBDDs.

\Rightarrow Semi-canonical representation of formulas.

Literature

A. Mishchenko, S. Chatterjee, R. Jiang, and R. K. Brayton: FRAIGs: A unifying representation for logic synthesis and verification; ERL Technical Report, EECS Dept., UC Berkeley, March 2005.

2.11 Other Calculi

Ordered resolution

Tableau calculus

Hilbert calculus

Sequent calculus

Natural deduction

see next chapter

3 First-Order Logic

First-order logic

- formalizes fundamental mathematical concepts
- is expressive (Turing-complete)
- is not too expressive (e. g. not axiomatizable: natural numbers, uncountable sets)
- has a rich structure of decidable fragments
- has a rich model and proof theory

First-order logic is also called (first-order) *predicate logic*.

3.1 Syntax

Syntax:

- non-logical symbols (domain-specific)
⇒ terms, atomic formulas
- logical connectives (domain-independent)
⇒ Boolean combinations, quantifiers

Signatures

A signature $\Sigma = (\Omega, \Pi)$ fixes an alphabet of non-logical symbols, where

- Ω is a set of *function symbols* f with *arity* $n \geq 0$, written $\text{arity}(f) = n$,
- Π is a set of *predicate symbols* P with *arity* $m \geq 0$, written $\text{arity}(P) = m$.

Function symbols are also called *operator symbols*.

If $n = 0$ then f is also called a *constant (symbol)*.

If $m = 0$ then P is also called a *propositional variable*.

We will usually use

b, c, d for constant symbols,

f, g, h for non-constant function symbols,

P, Q, R, S for predicate symbols.

Convention: We will usually write $f/n \in \Omega$ instead of $f \in \Omega$, $\text{arity}(f) = n$ (analogously for predicate symbols).

Refined concept for practical applications:

many-sorted signatures (corresponds to simple type systems in programming languages); no big change from a logical point of view.

Variables

Predicate logic admits the formulation of abstract, schematic assertions. (Object) variables are the technical tool for schematization.

We assume that X is a given countably infinite set of symbols which we use to denote *variables*.

Terms

Terms over Σ and X (Σ -terms) are formed according to these syntactic rules:

$$\begin{array}{l} s, t, u, v ::= x \quad , x \in X \quad \text{(variable)} \\ \quad \quad \quad | f(s_1, \dots, s_n) \quad , f/n \in \Omega \quad \text{(functional term)} \end{array}$$

By $T_\Sigma(X)$ we denote the set of Σ -terms (over X). A term not containing any variable is called a *ground term*. By T_Σ we denote the set of Σ -ground terms.

In other words, terms are formal expressions with well-balanced parentheses which we may also view as marked, ordered trees. The markings are function symbols or variables. The nodes correspond to the *subterms* of the term. A node v that is marked with a function symbol f of arity n has exactly n subtrees representing the n immediate subterms of v .

Atoms

Atoms (also called atomic formulas) over Σ are formed according to this syntax:

$$\begin{array}{l} A, B ::= P(s_1, \dots, s_m) \quad , P/m \in \Pi \quad \text{(non-equational atom)} \\ \quad \quad \quad \left[\quad | \quad (s \approx t) \quad \quad \quad \text{(equation)} \quad \right] \end{array}$$

Whenever we admit equations as atomic formulas we are in the realm of *first-order logic with equality*. Admitting equality does not really increase the expressiveness of first-order logic (see next chapter). But deductive systems where equality is treated specifically are much more efficient.

Literals

$$\begin{array}{l} L ::= A \quad (\text{positive literal}) \\ \quad | \quad \neg A \quad (\text{negative literal}) \end{array}$$

Clauses

$$\begin{array}{l} C, D ::= \perp \quad (\text{empty clause}) \\ \quad | \quad L_1 \vee \dots \vee L_k, \quad k \geq 1 \quad (\text{non-empty clause}) \end{array}$$

General First-Order Formulas

$F_\Sigma(X)$ is the set of first-order formulas over Σ defined as follows:

$$\begin{array}{l} F, G, H ::= \perp \quad (\text{falsum}) \\ \quad | \quad \top \quad (\text{verum}) \\ \quad | \quad A \quad (\text{atomic formula}) \\ \quad | \quad \neg F \quad (\text{negation}) \\ \quad | \quad (F \wedge G) \quad (\text{conjunction}) \\ \quad | \quad (F \vee G) \quad (\text{disjunction}) \\ \quad | \quad (F \rightarrow G) \quad (\text{implication}) \\ \quad | \quad (F \leftrightarrow G) \quad (\text{equivalence}) \\ \quad | \quad \forall x F \quad (\text{universal quantification}) \\ \quad | \quad \exists x F \quad (\text{existential quantification}) \end{array}$$

Notational Conventions

We omit parentheses according to the conventions for propositional logic.

$\forall x_1, \dots, x_n F$ and $\exists x_1, \dots, x_n F$ abbreviate $\forall x_1 \dots \forall x_n F$ and $\exists x_1 \dots \exists x_n F$.

We use infix-, prefix-, postfix-, or mixfix-notation with the usual operator precedences.

Examples:

$$\begin{array}{lll} s + t * u & \text{for} & +(s, *(t, u)) \\ s * u \leq t + v & \text{for} & \leq (*(s, u), +(t, v)) \\ -s & \text{for} & -(s) \\ s! & \text{for} & !(s) \\ |s| & \text{for} & |-(s) \\ 0 & \text{for} & 0() \end{array}$$